

## 25-2. Module Groups

### Note

When using the I/O Builder to configure the Valve Positioner (VP) module, note that whatever voltage/current description is displayed in the Slot position at the top of the window does **NOT** impact the configuration of the VP module.

### 25-2.1. Electronic Modules

There are two Electronics module groups for the Valve Positioner module:

- 1C31194G01 provides 17 Volts AC peak-to-peak 1 KHz LVDT drive.
- 1C31194G02 provides 23.75 Volts AC peak-to-peak 3 KHz LVDT drive.

### 25-2.2. Personality Modules

There are four Personality module groups for the Valve Positioner module:

- 1C31197G01 has 330 Ohm resistors that provide up to  $\pm 24.9$  mA into 82 ohm servo coils. Use with any Valve Positioner Electronics module.
- 1C31197G02 has 360 Ohm resistors that provide up to 16.8 mA into 250 ohm servo coils. Use with any Valve Positioner Electronics module.
- 1C31197G03 has 240 Ohm resistors that provide up to 8.3 mA into 1000 ohm servo coils. Use with any Valve Positioner Electronics module.
- 1C31197G04 has 160 Ohm resistors that provide up to 36 mA into 125 ohm servo coils. Only two coils may be driven by 1C31197G04. Use with any Valve Positioner Electronics module. The C3+ and C3- coil outputs are not available.

Table 25-1. Valve Positioner Subsystem <sup>1</sup>

Range	Channels	Electronic Module	Personality Module
<b>17 Volts AC peak-to-peak 1 KHz or 23.75 Volts AC peak-to-peak 3 KHz to an LVDT</b> 24.8 mA into three 82 ohm coils	8	1C31194G01 or 1C31194G02	1C31197G01
<b>23.75 Volts AC peak-to-peak 3 KHz or 17 Volts AC peak-to-peak 1 KHz to an LVDT</b> 16.8 mA into three 250 ohm coils	8	1C31194G02 or 1C31194G01	1C31197G02
<b>23.75 Volts AC peak-to-peak 3 KHz or 17 Volts AC peak-to-peak 1 KHz to an LVDT</b> 8.3 mA into three 1000 ohm coils	8	1C31194G02 or 1C31194G01	1C31197G03
<b>23.75 Volts AC peak-to-peak 3 KHz or 17 Volts AC peak-to-peak 1 KHz to an LVDT</b> 36 mA into two 125 ohm coils	8	1C31194G02 or 1C31194G01	1C31197G04

When using the Point Builder to define points for a Valve Positioner module, only the following point types are valid for each channel:

<u>I/O</u> <u>Channel</u>	<u>Name</u>	<u>Type</u>	<u>Input Source or</u> <u>Output Destination</u>	<u>Terminal Block</u> <u>Connection</u> <sup>2</sup>
1	Shutdown Status	Input	Valve Positioner	DI1
2	Auxiliary (wetting) Voltage Sense	Input	Valve Positioner	DI2
3	SLIM ON Signal	Input	Valve Positioner	DI3
4	Position Feedback	Input	Valve Positioner	
5	Coil 1 Voltage (Read-back)	Input	Valve Positioner	Coil 1
6	Coil 2 Voltage (Read-back)	Input	Valve Positioner	Coil 2
7	Coil 3 Voltage (Read-back)	Input	Valve Positioner	Coil 3
8	Raw Demodulator Voltage	Input	Valve Positioner	

<sup>1</sup> This module will provide an interface between an Ovation Controller and **ONE** Electro-Hydraulic (EH) servo-valve actuator in the field. To use this module, the MASTATION algorithm must reside in the Ovation Controller. Refer to “[Ovation Algorithm Reference Manual](#)” (R3-1100) for detailed information about the MASTATION algorithm.

<sup>2</sup> The terminal block connection depends upon the application being used. Refer to wiring diagrams.

### 25-2.3. Firmware Levels

This table lists all VP module firmware releases that added additional functionality to the VP.

VP Firmware Level (Electronics Module)	VP Revision Level (Electronics Module)	Firmware Features
<b>0F</b>	9	Added support for the following: Calibration from the Controller using graphics.  Upload/download of calibration constants to and from the Controller.  New tuning constants kServo and kServoDb to replace hard-coded constants. They add flexibility in dealing with differing coil impedances.  Reduction of valve calibration time.
<b>0C</b>	6	Added support for VP Redundancy.
<b>0B</b>	5	First full production firmware release.

## 25-3. Specifications

### Electronics Module (1C31194) Personality Module (1C31197)

**Table 25-2. Valve Positioner Module Specifications**

Description	Value
Valve positioning field interface channels	One
LVDT position feedback Input range	25 V AC peak to peak (LVDT A and LVDT B) maximum
LVDT position feedback input impedance	20 k $\Omega$ (LVDT A and LVDT B) differential input with floating source 10 k $\Omega$ (LVDT A and LVDT B) one input line referenced to common
LVDT excitation output voltage	17 V AC peak to peak $\pm$ 11% @ 1.0 kHz $\pm$ 10% (1C31194G01) 23.75 V AC peak to peak $\pm$ 11% @ 3.0 kHz $\pm$ 10% (1C31194G02) 500 $\Omega$ minimum load impedance (1C31194G01 & G02) Drift 0.5% max/yr
Peak servo valve coil output voltages	(1C31197G01) up to three 82 $\Omega$ coils, $\pm$ 2.04 V (1C31197G02) up to three 250 $\Omega$ coils, $\pm$ 4.20 V (1C31197G03) up to three 1000 $\Omega$ coils, $\pm$ 8.26 V (1C31197G04) up to two 125 $\Omega$ coils, $\pm$ 4.5 V
Servo valve coil output voltage accuracy	0.4% of full scale output
Field interface dielectric isolation	1000 V DC The valve positioning field interface has 50 V and 150 V short term isolation from the logic common/Ovation I/O bus
SLIM interface serial port	RS-485
SLIM interface serial port baud rate	9600
SLIM interface dielectric isolation	$\pm$ 1000 V DC
Local serial port	RS-232, non-isolated
Local serial port baud rate	19200
SHUTDOWN digital input Input voltage range Propagation delay of contact change of state Cable length Dielectric isolation	24 V/48 V DC nominal 18 V DC minimum, 60 V DC maximum 1.9 mSec minimum; 25.5 mSec maximum 1000 feet maximum (cable capacitance $\leq$ 50 pF/ft) $\pm$ 1000 V DC